

Similarities between Timing Constraints

Towards Interchangeable Constraint Models for Real-World Software Systems

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Background

Software for real-world systems

- **System Complexity:** guarantees of exact system behavior are impractically expensive [Lee, 2005].
- **Operating Environment:** The unpredictable nature of the environments in which software systems operate determines that their interactions with the outer world may not be totally expected [Jackson et al., 2007].
- **Computational Intractability:** From a theoretical point of view, achieving exactness in the verification of system properties is sometimes intractable [Alur and Dill, 1994].

$$\square (p \rightarrow \diamond_{=5} q)$$

Related Works [Huang et al., 2003, Huang et al., 2004]

Similarities between timed state sequences

- A *timed state sequence* is a linear structure
 $(\delta_0, I_0), (\delta_1, I_1), (\delta_2, I_2), \dots$ where $\delta_i \subseteq Prop$

$$\bar{\tau}_1 \begin{array}{c} \lceil \quad \delta_0 \quad \bowtie \quad \delta_1 \quad \bowtie \quad \delta_2 \quad \bowtie \quad \delta_3 \quad \bowtie \quad \delta_4 \quad \dots \\ \hline 0 \qquad \qquad 1.1 \qquad \qquad 2.3 \qquad \qquad 3.3 \qquad \qquad 4.4 \qquad \dots \end{array}$$

$$\bar{\tau}_2 \begin{array}{c} \lceil \quad \delta_0 \quad \bowtie \quad \delta_1 \quad \bowtie \quad \delta_2 \quad \bowtie \quad \delta_3 \quad \bowtie \quad \delta_4 \quad \dots \\ \hline 0 \qquad \qquad 1.2 \qquad \qquad 2.2 \qquad \qquad 3.4 \qquad \qquad 4.2 \qquad \dots \end{array}$$

- Absolute displacement between two interval sequences \bar{I} and \bar{I}'

$$D_a^{\mathcal{I}}(\bar{I}, \bar{I}') = \left[d_{a_{\text{inf}}}^{\mathcal{I}}(\bar{I}, \bar{I}'), d_{a_{\text{sup}}}^{\mathcal{I}}(\bar{I}, \bar{I}') \right]$$

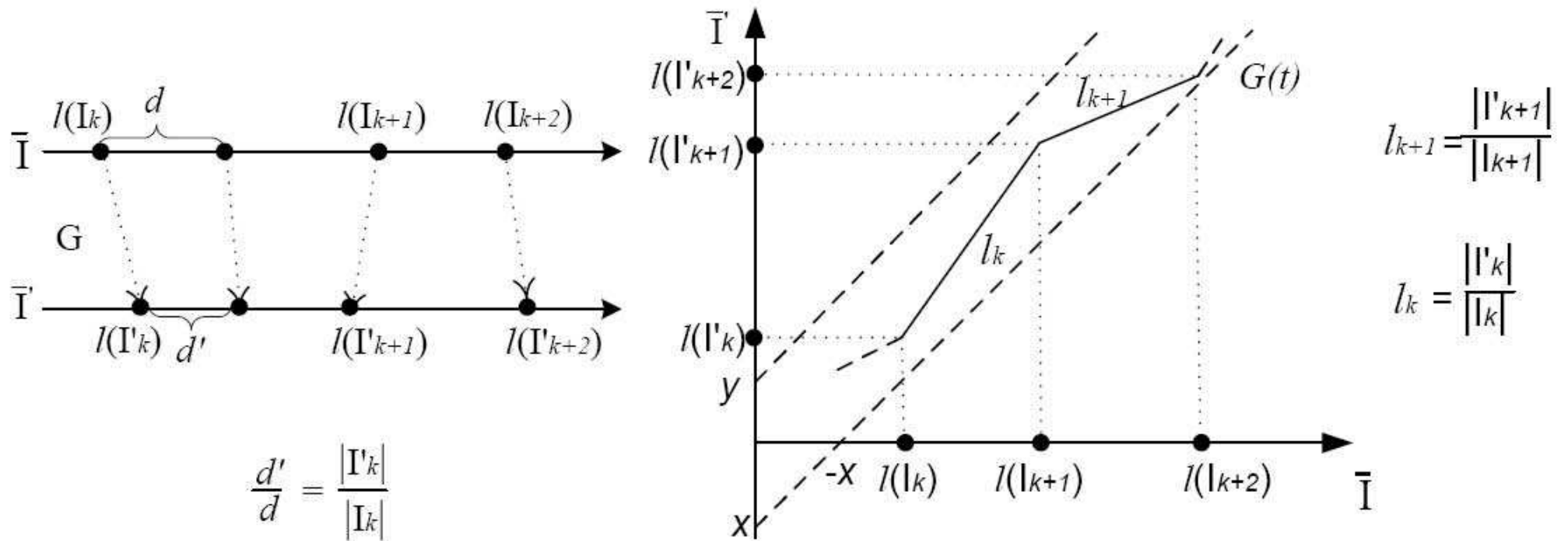
where

$$d_{a_{\text{sup}}}^{\mathcal{I}}(\bar{I}, \bar{I}') = \sup \{ l(I'_i) - l(I_i) \mid i < n(\bar{I}) \}$$

$$d_{a_{\text{inf}}}^{\mathcal{I}}(\bar{I}, \bar{I}') = \inf \{ l(I'_i) - l(I_i) \mid i < n(\bar{I}) \}$$

Related Works [Huang et al., 2003, Huang et al., 2004]

● Absolute $[x, y]$ -tube function

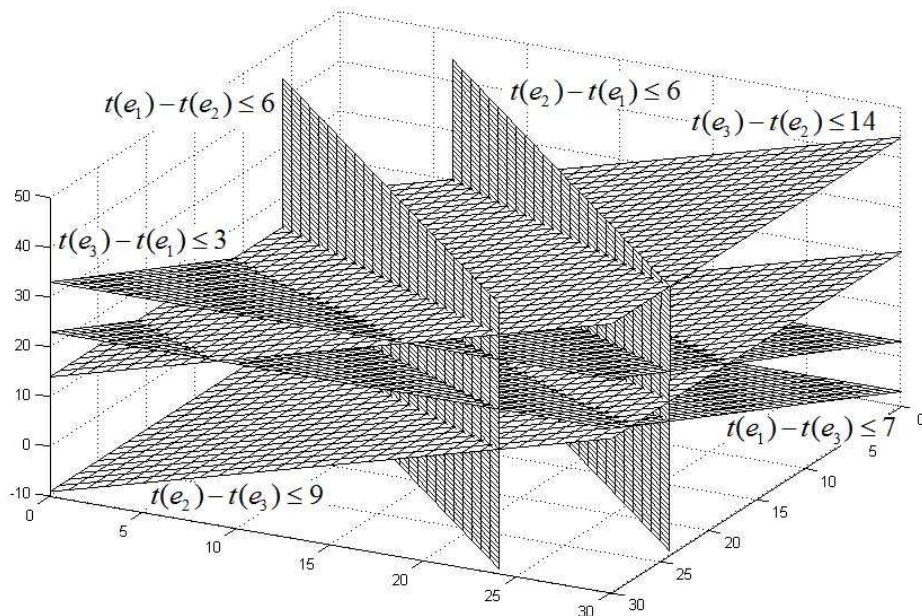


Let \bar{I} and \bar{I}' be two interval sequences. There exists an absolute $[x, y]$ -tube function from \bar{I} to \bar{I}' iff $D_a^{\bar{I}}(\bar{I}, \bar{I}') \subseteq [x, y]$

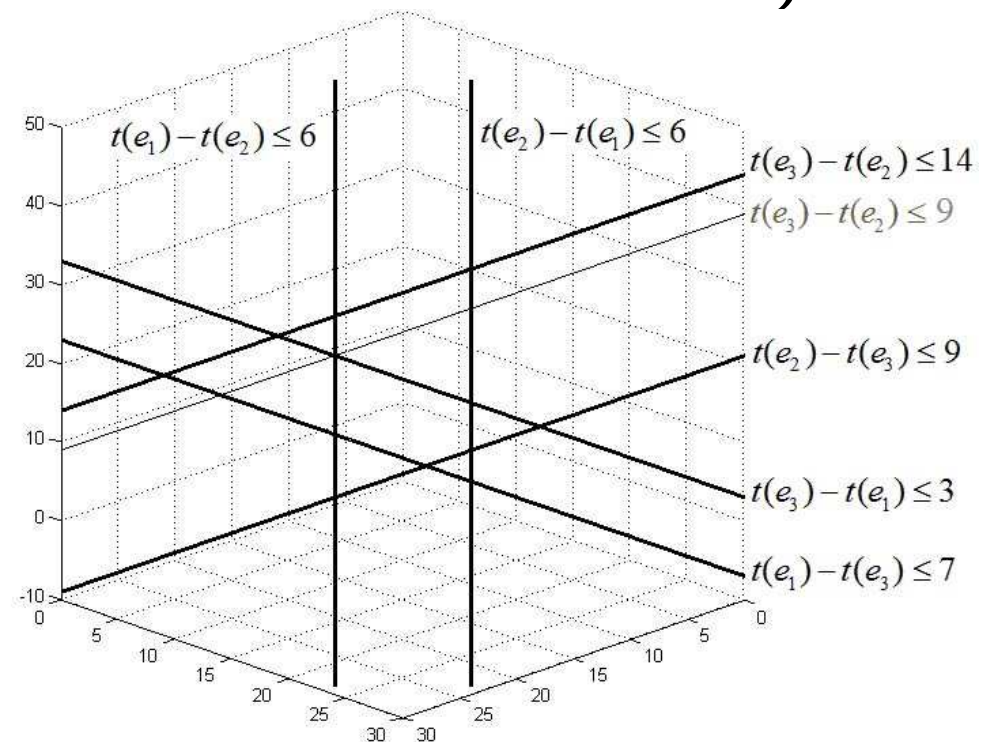
- Linear timing constraints

$$\left\{ \begin{array}{l} t(e_1) - t(e_2) \leq 6, \quad t(e_2) - t(e_1) \leq 6, \quad t(e_1) - t(e_3) \leq 7, \\ t(e_3) - t(e_1) \leq 3, \quad t(e_2) - t(e_3) \leq 9, \quad t(e_3) - t(e_2) \leq 14 \end{array} \right\}$$

- Timed trace set



(a)

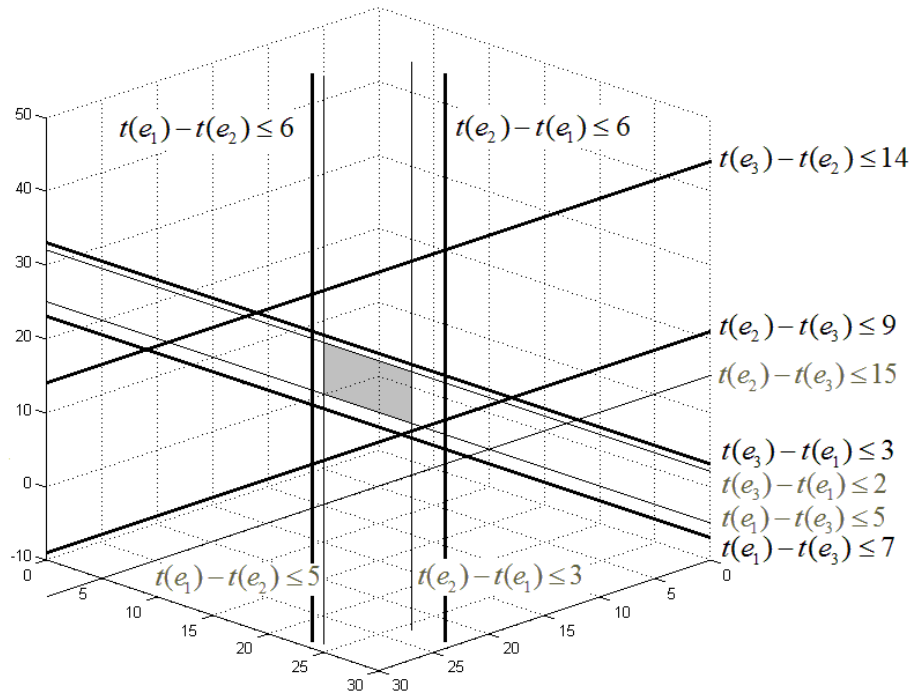


(b)

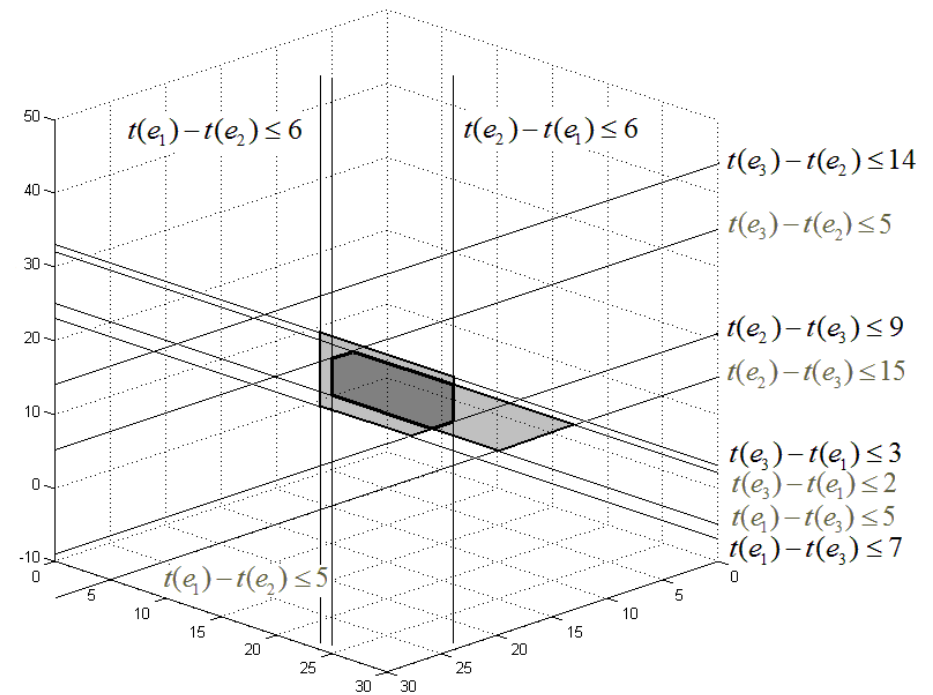
Difference relations between every *pairs* of events determine the shape of the trace polyhedron.

Timed Trace Inclusions and Intersections

● Timed Trace Inclusions and Intersections



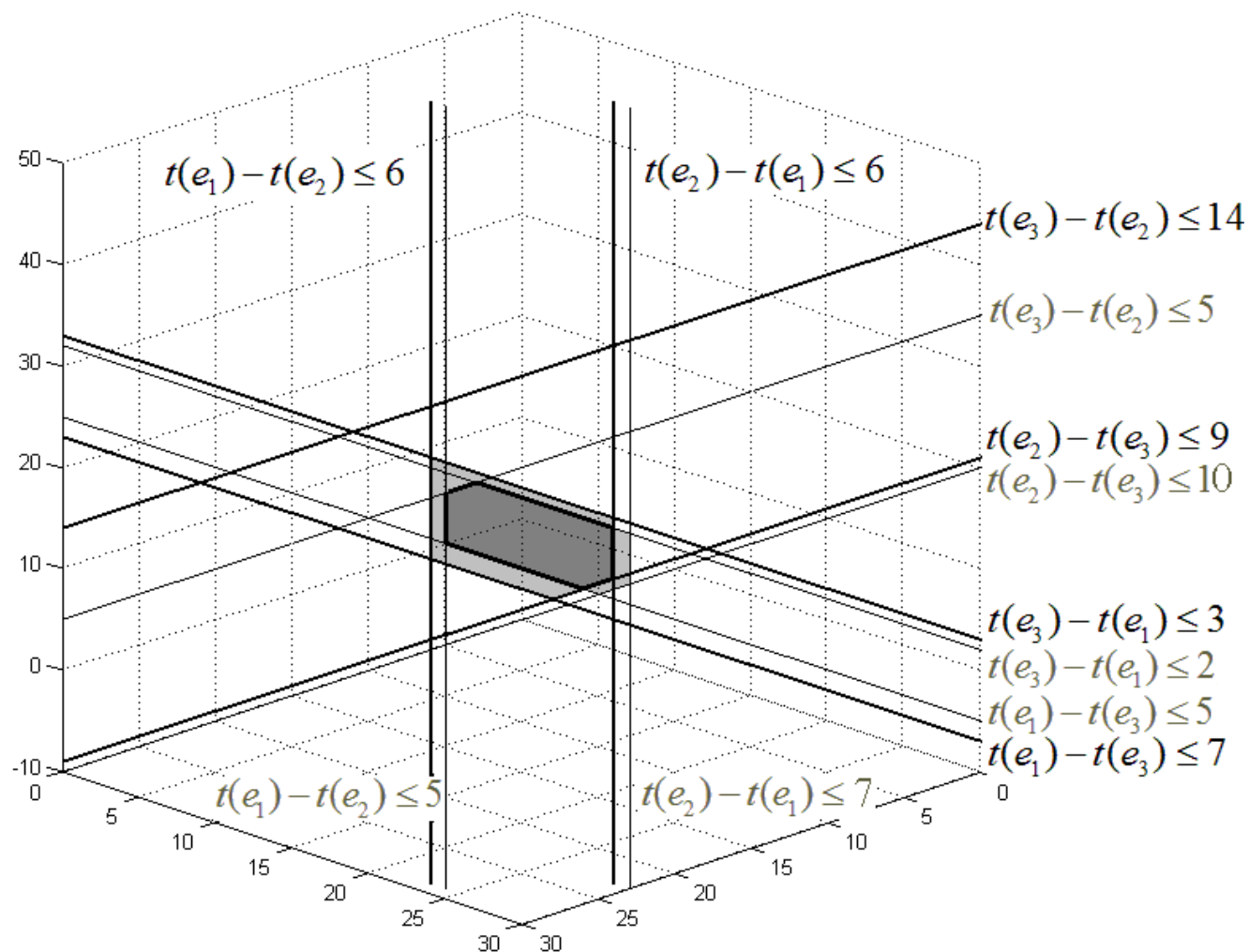
(c) Inclusion



(d) Intersection

Timed Trace Similarities

- Similarities between timed trace sets



Proposed Metrics: Absolute Differences

- Absolute differences

$$D_a(C, C') = [d_{a_{\text{inf}}}(C, C'), d_{a_{\text{sup}}}(C, C')]$$

where

$$d_{a_{\text{sup}}}(C, C') = \sup \left\{ d_{i,j}^* - d'_{i,j} \mid i = 1, \dots, n, j = 1, \dots, n, i \neq j \right\}$$

$$d_{a_{\text{inf}}}(C, C') = \inf \left\{ d_{i,j}^* - d'_{i,j} \mid i = 1, \dots, n, j = 1, \dots, n, i \neq j \right\}$$

For example, in the previous slide, the absolute difference between the two timed trace sets is derived as

$$d_{a_{\text{sup}}}(C, C') = \sup \{6 - 5, 6 - 7, 7 - 5, 3 - 2, 9 - 10, 9^a - 5\} = 4,$$

$$d_{a_{\text{inf}}}(C, C') = \inf \{6 - 5, 6 - 7, 7 - 5, 3 - 2, 9 - 10, 9 - 5\} = -1, \text{ and}$$

$$D_a(C, C') = [-1, 4].$$

^anote that $d_{3,2}^* = 9$ instead of 14

Proposed Metrics: Absolute Differences

Proposition:(This directly follows from the inclusion theorem)

- Systems satisfying timing constraint set C will satisfy timing constraint set C' when every constraint in C' is incremented by $d_{a_{\text{sup}}}(C, C')$, i.e., for all $i \neq j$: $d'_{i,j} + d_{a_{\text{sup}}}(C, C')$; and symmetrically,
- systems satisfying timing constraint set C' will satisfy timing constraint set C when every constraint in C is incremented by $d_{a_{\text{sup}}}(C', C)$, i.e., for all $i \neq j$: $d_{i,j} + d_{a_{\text{sup}}}(C', C) = d_{i,j} + d_{a_{\text{inf}}}(C, C')$.

Transitive relations can be bounded by:

$$D_a(C, C'') \subseteq [d_{a_{\text{inf}}}(C, C') + d_{a_{\text{inf}}}(C', C''), d_{a_{\text{sup}}}(C, C') + d_{a_{\text{sup}}}(C', C'')]$$

Proposed Metrics: Relative Differences

- Relative differences

$$D_r (C, C') = [d_{r_{\text{inf}}} (C, C'), d_{r_{\text{sup}}} (C, C')]$$

where

$$d_{r_{\text{sup}}} (C, C') = \sup \left\{ \frac{d_{i,j}^*}{d'_{i,j}^*} \mid i = 1, \dots, n, j = 1, \dots, n, i \neq j \right\}$$

$$d_{r_{\text{inf}}} (C, C') = \inf \left\{ \frac{d_{i,j}^*}{d'_{i,j}^*} \mid i = 1, \dots, n, j = 1, \dots, n, i \neq j \right\}$$

For example, the relative difference between the two timed trace sets is

$$d_{r_{\text{sup}}} (C, C') = \sup \{6/5, 6/7, 7/5, 3/2, 9/10, 9/5\} = 9/5,$$

$$d_{r_{\text{inf}}} (C, C') = \inf \{6/5, 6/7, 7/5, 3/2, 9/10, 9/5\} = 6/7, \text{ and}$$

$$D_r (C, C') = [6/7, 9/5].$$

Conjecture: The proportion of the “volume” of the intersection in that of C is lower bounded by $\frac{1}{d_{r_{\text{sup}}}(C, C')}$; and symmetrically, the proportion of the “volume” of the intersection in that of C' is lower bounded by $\frac{1}{d_{r_{\text{sup}}}(C', C)} = d_{r_{\text{inf}}}(C, C')$.

References

References

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